

# SHARP GP2Y0A41SK0F IR ranger sensor (4-30cm) SKU:SEN0143

---

## Specifications

- Output : analog output
- Detection Range : 4-30cm
- Voltage : 4.5~5.5V
- Current : 33mA
- Size : 40x20x13.5 mm

## formulas

### Formulas

These formulas are derived from the Sharp datasheets to compute distance.

The formula to translate SensorValue into Distance for Sharp 10-80cm analog sensors is:

$$\text{Distance (cm)} = 4800 / (\text{SensorValue} - 20)$$

This formula is only valid over the SensorValue range 80-500.

The formula to translate SensorValue into Distance for Sharp 20-150cm analog sensors is:

$$\text{Distance (cm)} = 9462 / (\text{SensorValue} - 16.92)$$

This formula is only valid over the SensorValue range 80-490.

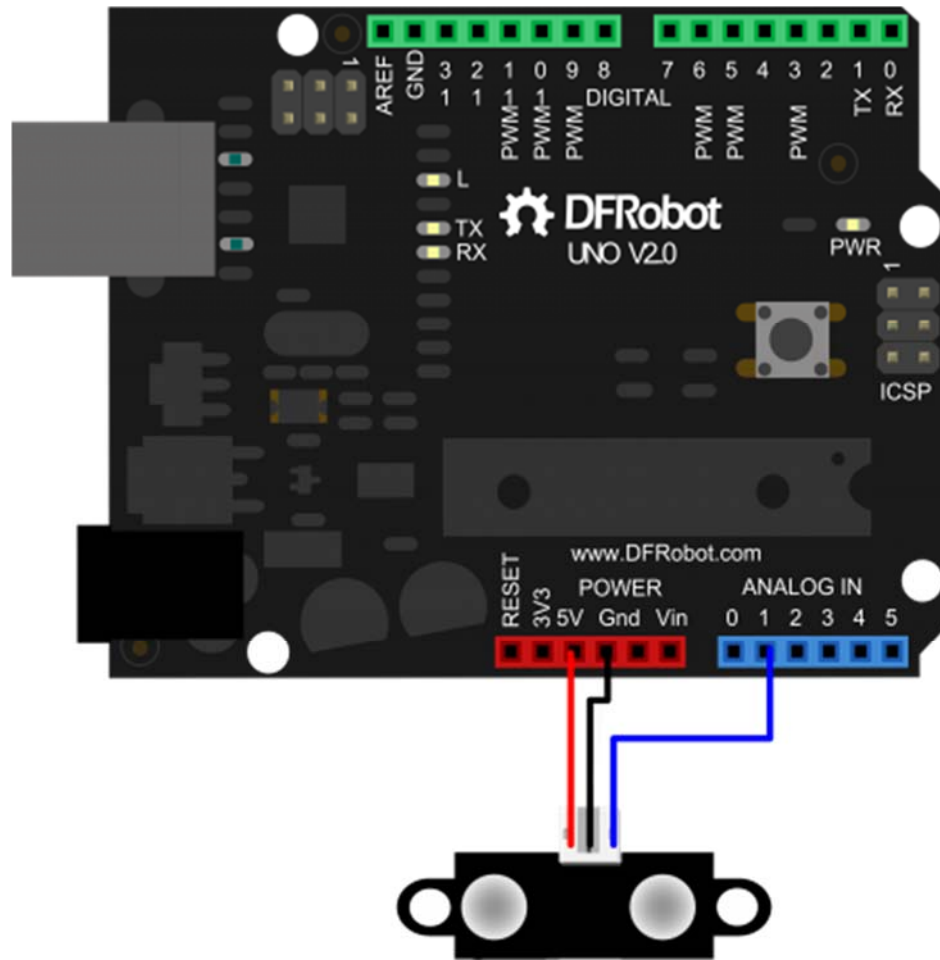
The formula to translate SensorValue into Distance for Sharp 4-30cm analog sensor is:

$$\text{Distance (cm)} = 2076 / (\text{SensorValue} - 11)$$

This formula is only valid over the SensorValue range 80-530.

For digital distance sensors, SensorValue will be greater than 200 if the distance of the object being measured is less than the detection distance of the sensor. Otherwise the SensorValue will be less than 200.

# Connection Diagram



# Sample Code

```
/*  
***** start code *****/  
*  
*   created      2013-07-29  
*   by           lisper (leyapin@gmail.com)  
*   function     test GP2Y0A41SK0F  
*  
*/  
  
//connect gp2d120x to A1  
#define pin A1
```

```

void setup () {
    Serial.begin (9600);
    pinMode(pin, INPUT);
}

void loop () {
    uint16_t value = analogRead (pin);
    double distance = get_IR (value); //Convert the analog voltage to the
distance
    Serial.println (value);           //Print the data to the ardui
no serial monitor
    Serial.print (distance);
    Serial.println (" cm");
    Serial.println ();
    delay (500);                      //Delay 0.5s
}

//return distance (cm)
double get_IR (uint16_t value) {
    if (value < 16) value = 16;
    return 2076.0 / (value - 11.0);
}

/***** end code *****/

```